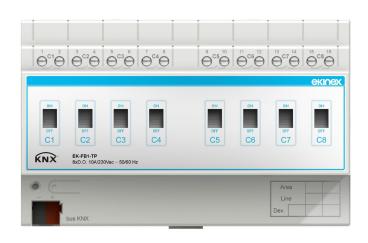


Application manual





KNX binary output module EK-FA1-TP 4-channel EK-FB1-TP 8-channel



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1 Scope of the document

This application manual describes application details for the A1.0 release of the ekinex[®] KNX binary output modules EK-FA1-TP (4 channels) and EK-FB1-TP (8 channels).

The document is aimed at the system configurator as a description and reference of device features and application programming. For installation, mechanical and electrical details of the device please refer to the technical description datasheet.

Application manual and application programs for ETS are available for download at www.ekinex.com.

| <i>Item</i> | File name (## = release) | Version | Device rel. | Update |
|----------------------|--|---------|-------------|-----------|
| Technical datasheet | STEKFA1TP_EN.pdf | - | | |
| reclinical datasneet | STEKFB1TP_EN.pdf | | | |
| Application manual | MAEKFA1FB1TP_EN.pdf | - | A1.0 | 02 / 2014 |
| Application program | APEKFA1TP##.knxprod APEKFB1TP##.knxprod | - | | |

You can access the most up-to-date version of the full documentation for the device using following QR codes:

For the 4-channel interface EK-FA1-TP:









2 Product description

The ekinex® binary output modules EK-FA1-TP and EK-FB1-TP are S-mode KNX modular devices for independent switching respectively of 4 or 8 electrical loads; to this purpose, the outputs of the devices are equipped with potential-free relay contacts.

The two devices differ only for the number of the output channels; their operation is the same in every respect, except for the fact that, for the smaller unit, the parameters and communication objects bound to the upper 4 channels are not available. In this manual, both devices will be referenced interchangeably; only where differences exist, they will be explicitly highlighted.

The device is equipped with an integrated bus communication module and is designed for rail mounting in distribution boards.

For operation, the devices receives KNX telegrams from the bus, sent by another KNX device (such as a pushbutton, a sensor, a display, a timer, etc.); these telegrams cause the activation or deactivation of one or more relays.

Manual operation of an output channel is also possible by using the corresponding lever on the front side; the position of the lever simultaneously acts as an indicator of the switching status of the relay. Bistable relays ensure that the status of the outputs can be maintained even in case of failure of the bus voltage.

The device is powered by the KNX bus line with a 30 VDC SELV voltage and does not require auxiliary power; all required operation voltages for the input channels are produced inside the device. A reservoir capacitor is built in in order to supply the required power to the device while maintaining compliance to the KNX-prescribed bus power drain.



For further technical information, please also refer to the product datasheets STEKFA1TP_EN.pdf and STEKFB1TP_EN.pdf available on the ekinex website www.ekinex.com.



3 Switching, display and connection elements

The device is equipped with:

- a programming pushbutton and a programming LED
- switch levers for manual operation
- terminals for output load connection
- terminals for the KNX bus line connection

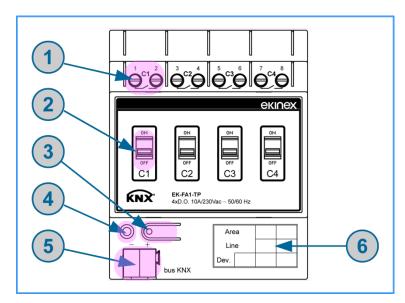


Fig. 1 - Switching, display and connection elements

- 1) Terminal blocks for outputs
- 2) Switch levers for manual operation and status feedback
- 3) Programming pushbutton
- 4) Programming LED
- 5) Terminal block for KNX bus line
- 6) Field for physical address



4 Configuration

The exact functionality of the device depends on the software settings.

In order to configure and commission the device you need ETS4 or later releases and the proper ekinex® application program, either APEKFA1TP.knxprod or APEKFB1TP.knxprod, which can be downloaded from the ekinex® website www.ekinex.com.

The application program allows the configuration of all working parameters for the device.

The device-specific application program has to be loaded into ETS or, as alternative, the whole ekinex® product database can be loaded; at this point, all the instances of the selected device type can be added to the project.

For every single device, ETS allows to set the operating parameters individually for each input as described in detail in the following chapters.

The configuration can, and usually will, be performed completely offline; the actual transfer of the programmed configuration to the device takes place in the commissioning phase.

| Product code | EAN | No. of channels | ETS application software (## = release) | Communication objects (max nr.) | Group adresses (max nr.) |
|--------------|---------------|-----------------|--|---------------------------------------|--------------------------------|
| EK-FA1-TP | 8018417181139 | 4 | APEKFA1TP##.knxprod | 76 | 254 |
| EK-FB1-TP | 8018417181146 | 8 | APEKFB1TP##.knxprod | 152 | 254 |



Configuration and commissioning of KNX devices require specialized skills. To acquire these skills, you should attend training courses at a training center certified by KNX.

For further information: www.knx.org

5 Commissioning

After the device has been configured within the ETS project according to user requirements, the commissioning of the device requires the following activities:

- electrically connect the device, as described in the product datasheet, to the bus line on the final network or through a purposely setup network for programming;
- apply power to the bus;
- switch the device operation to programming mode by pressing the programming pushbutton located on the front side of the housing. In this mode of operation, the programming LED is turned on steady;
- upload the configuration (including the physical address) to the device with the ETS program.

At the end of the upload, the operation of the device automatically returns to normal mode; in this mode the programming LED is turned off. Now the device is programmed and ready for use on the bus.



6 Function description

After switching on the bus, which also acts as a power supply, the device becomes fully functional after a very short time needed for reinitialization. A further delay is programmable for the device to become active on the bus in order to avoid a bus traffic overload during the first moments of startup of the whole network.

In case of a bus power failure (voltage lower than 19 V for 1 s or more), the device becomes unreactive: the timing functions are not active, neither are the programmed group addresses.

As soon as the bus voltage is restored, the device will resume operation in its previous state (which is saved on power fail), unless different initialization settings are programmed.

6.1 Offline operation

A fully unprogrammed device causes no activity on the bus; it can be operated in manual mode by toggling the relay levers like a normal manual relay switch. Switching relay causes direct operation on output.

6.2 Online operation

The device is a switching endpoint, which activates its switch channels according to telegrams sent by other devices on the bus.

It also incorporates additional features such as e.g. timing and logic combination features, described in the following chapters.

6.2.1 Software working cycle

The software working cycle can be described as follows:

- Handle incoming telegrams from the KNX bus to update internal state variables
- Implement timing functions and other inbuilt functions to determine effect on physical outputs;
- Drive output relays outputs according to output status
- Respond to bus messages requesting feedback on the status of the outputs and of the device.

There are also special events on which it is possible to trigger additional features. These events are the bus failure and recovery, and the download of a new configuration with ETS.

6.2.2 State variables (Communication objects)

The determination of the status of physical outputs is made basing on internal state variables. These state variables, once assigned a group address, are actually KNX communication objects, which allows other devices on the bus to exploit the features of the device.

State variables undergo the usual rules for communication objects, among which – for instance – the effect of flags to determine how the change of value affects the transmission of the objects.

6.2.3 Outputs

6.2.3.1 Output handling features

The outputs are of binary type, i.e. they can only assume On and Off as values; each channel can be driven independently.

Each output has a relay with a single-pole, single-throw contact rated 10 A at 230 V AC.



In the most simple case there is only one communication object per channel, "On-Off command", that switches each channel output directly with a message.

By setting the device parameters, it is possible to activate additional features, most of which will also affect the outputs. These features are:

- Relay inversion: allows to short contacts on the Off logical value and disconnect on the On value.
- Feedback: sends message on each switching operation or cyclically each period of time
- Time delay block: allows to perform the actual relay switch with a programmable delay. It is available (with separate delay settings) both for the On-Off and for the Off-On transition.
- Staircase function: performs a retriggerable time period activation of an output.
- Logic function: allows to compute the output value as a logic function based on the value of several communication objects.
- Lock and Force: these functions can temporarily force the output to fixed values and also perform high priority switching operations.
- Scene management: allows to save and recall a combination of state and values with a single telegram.
- Operating hours / Energy consumption counter: allows a limited tracking of energy consumption by accumulating "On" period durations over time.

The most significant functional blocks are described in the following scheme.

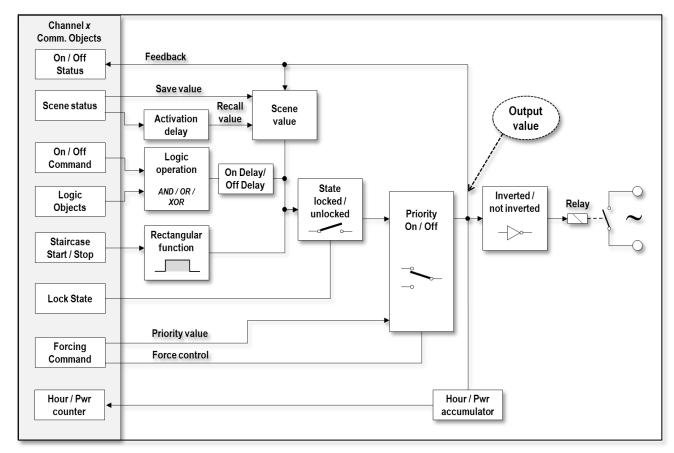


Fig. 2 - Functional blocks



6.2.3.2 Relay inversion

This feature inverts the status of the physical contact of a channel with respect to the exit status. Regardless of the "inversion" parameter setting, the following sections will always take "on" and "off" to be a reference to the <u>logical</u> status of the output, not the status of the relay contact switch.

6.2.3.3 Feedback

When feedback is enabled, a communication object corresponding to the status of the output is made available for reading by other devices on the bus. This object carries the actual state of the logic output, which is likely to be different from the command value because it includes the effect of all additional functions which may be active at the time.

If this communication object is defined, it is also transmitted on every state change, so it can be used to trigger events following the actual state change of an output; it is also possible to configure transmission at regular intervals.

Feedback telegrams are not sent if the relay levers are operated manually.

6.2.3.4 Time delay

The actual change of state of an output can be set to take place after a configurable delay from the change of the value of the corresponding communication object; this applies both to the on-off and the off-on transitions, each with its individually configurable delay value (Ton and Toff respectively).

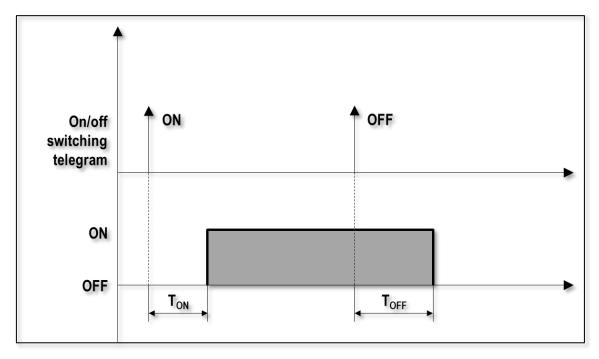


Fig. 3 - Time delay

6.2.3.5 Staircase function

This function is intended to provide a simple and flexible way to manage the switching of staircase lights. These have following peculiar requirements:

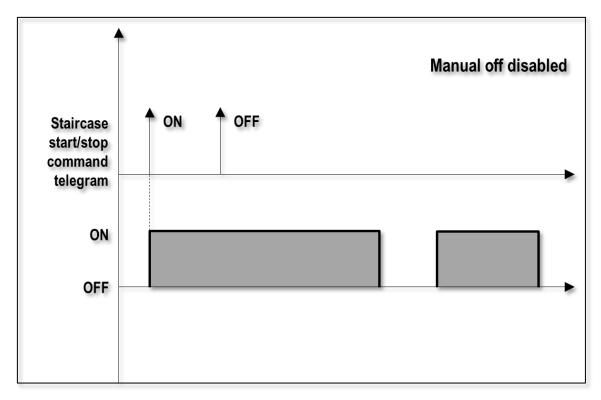
• The light is activated by a "start" command (e.g. through a pushbutton or a presence sensor), and normally remain lit for a programmed time duration;



- There is a provision to enable a "stop" (Manual Off) command, again through a pushbutton or other events, that allows to switch the light off before the programmed time expires (e.g. because the person who triggered the presence sensor has surely left the building through an exit);
- There is a provision to allow another "start" command (Retriggering), received during activation, to restart the time duration counter;
- A further optional "pre-warning" function allows to briefly switch off the load a certain time before expiration (both times, i.e. pause duration and time before expiration, are configurable) in order to warn the user that the activation time is about to end.



Following pictures show the *Manual Off* feature:



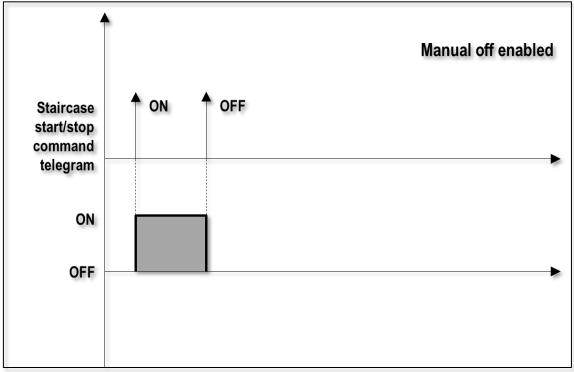
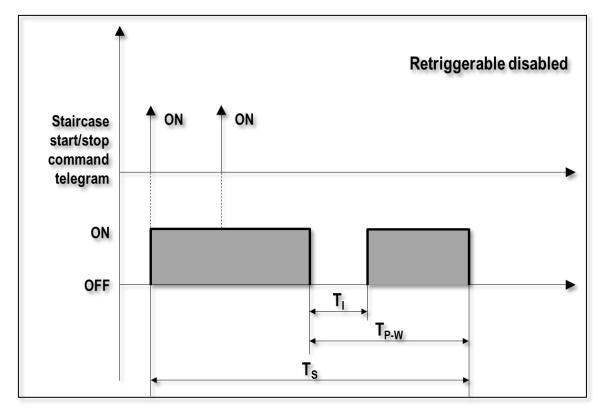


Fig. 4 - Manual Off feature



Following pictures show the Retrigger feature:



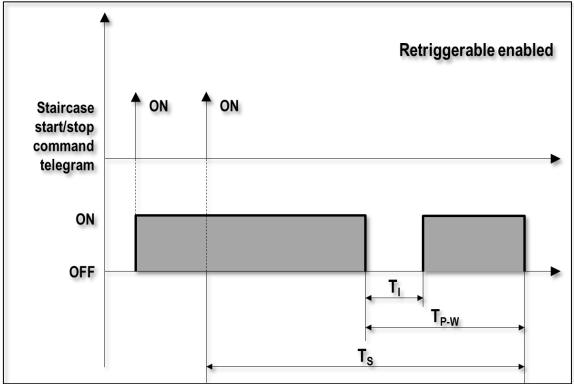
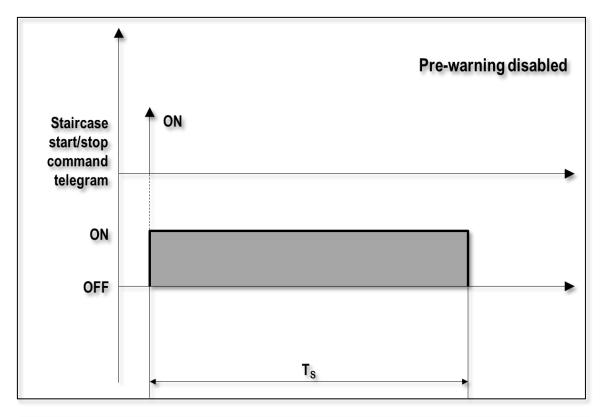


Fig. 5 - Retrigger feature



Following pictures show the *Pre-warning* feature:



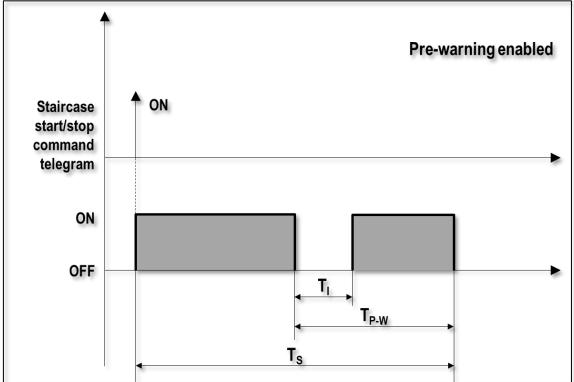


Fig. 6 - Pre-warning feature



6.2.3.6 Logic function

The device has a limited provision for the logic processing of internal variables in order to condition the status of outputs.

A given incoming output command can be used as an input to a logic block which operation is selectable between OR, AND and XOR (exclusive OR). Up to other 8 objects can be defined as additional inputs to the same block (each with an optional negation operation); these objects are directly accessible to other devices from the bus and they can be used as desired.

The input objects are logically combined as in following picture:

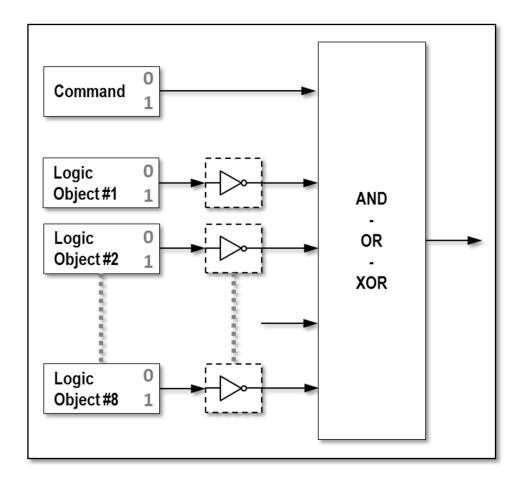


Fig. 7 - Logic functions

The logic combination block on the right works as follow according to which logical operation is selected:

- OR the output is ON whenever any one of the inputs is ON;
- AND the output is ON only if all of the inputs are ON;
- XOR the output is ON if an ODD number of inputs are ON.
 This latter operation is more intuitive when thinking of two inputs only: in this case, the output is ON when one input or the other is ON, but not both.

It must be noted that, in the above description, "input" and "output" are referred to the logical block; for the purpose of operation, the actual "inputs" are the logic objects, thus the optional inverters must be factored in.



This structure allows to implement fairly complex logical combinations; a more generic and powerful programming capability would add more complexity and therefore it would be far beyond the scope of an output module that is simple to use.

In the following pictures, the basic logic functions are illustrated, assuming the output command and one logic object are used:

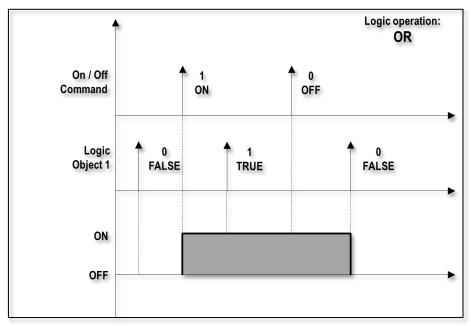


Fig. 8 - Logic OR function

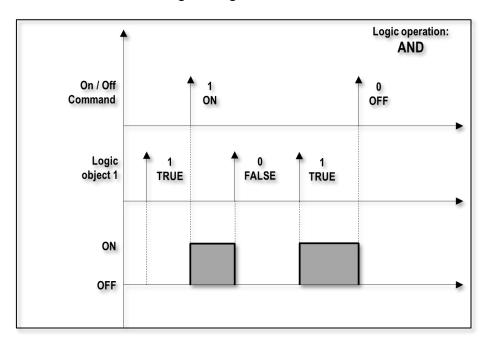


Fig. 9 - Logic AND function



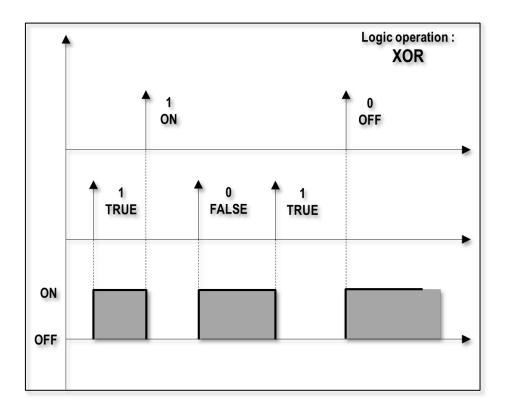


Fig. 10 - Logic XOR function



6.2.3.7 Lock function

If the locking feature is enabled, the operation of a channel can be inhibited by writing a value in a communication object. The value written is of the KNX type "enable"; please beware that the meaning of this value is "activate lock", which is not to be confused either with "enable locking function" or with "enable output". The meaning of the value can be optionally inverted through a configuration parameter (an "enable on" value can be interpreted as "lock off").

A locked output ignores the switching commands that are received for the duration of the lock, thereby maintaining the status it has upon lock entry. The status of the output can be set to a particular value both when the lock is set and when it is released; it is also possible to determine whether the lock status should be maintained or changed on recovery after a bus power-off.

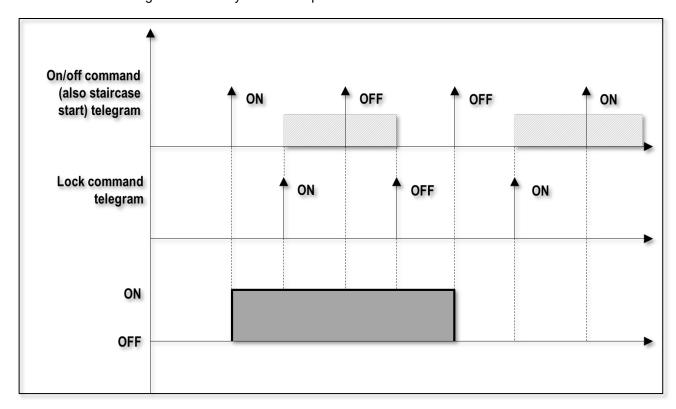


Fig. 11 - Lock function



6.2.3.8 Forcing function

The forced control is very similar to the basic direct command of the output value, but with the peculiarity that it overrides both the "regular" set value and every other value conditioning feature (i.e. logic function, staircase timing etc.).

It is possible to set what value the output should assume both when the output forcing is released and also on recovery after a bus power-off if forcing was previously in effect.

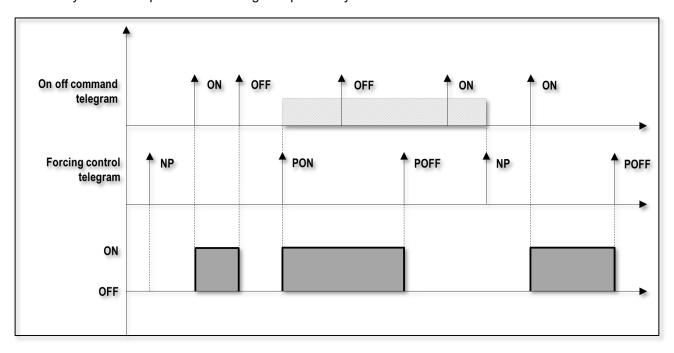


Fig. 12 - Forcing function

The "Force" command has priority over Locking (which acts on the ordinary on-off command); therefore, a locked output can still be operated through "Force" commands.

The KNX command code for the "Force" operation is a 2 bit value; the *priority* bit determines whether the output value must be forced, in which case the *value* bit is assigned to the output.

In the figure above, NP means that the *priority* bit is 0 (No Priority), while the PON and POFF codes indicate the values with *priority* = 1 and *value* respectively 1 or 0.

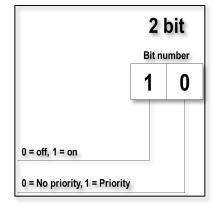


Fig. 13 - Force command bits



6.2.3.9 Scene management

Each output can be linked to up to 8 scene codes; when one of these scene codes is recalled through a bus command originated by any controller device, the output will assume a preset value. An additional delay can be defined for the output activation (or deactivation) from the moment the scene code is recalled.

The output value for a scene can either be fixed and chosen in the configuration phase, or it can be defined as reprogrammable through a Scene Learning command.

If this latter option is enabled (for each single output), whenever a Scene Learning command is received on the bus for a specific scene code to which the output has an association, the device will store the current output status value for that scene. This value will then be recalled in subsequent scene activations.

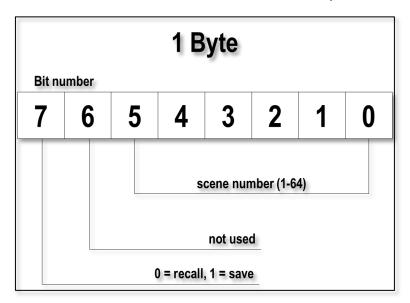


Fig. 14 - Scene store / recall command code

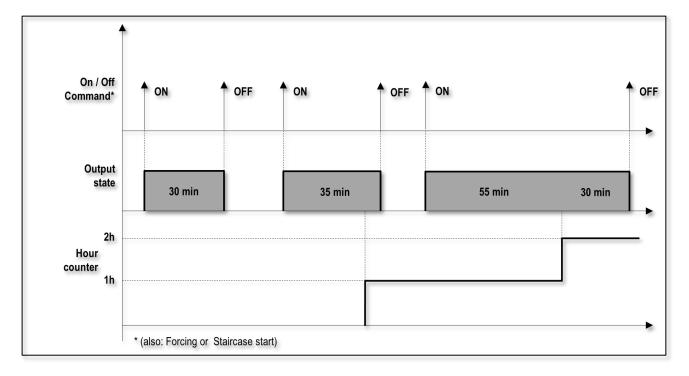


6.2.3.10 Operating hours / Energy consumption counter

For each output, an activation counter can be associated which accumulates the count of hours that the output passed in the "on" state. In terms of communication objects, this counter has the format of a KNX hour counter, thus it also has a "reset" command ad a "runout" alarm in case the maximum value is overflowed.

An additional parameter allows to define a conventional electrical power which is associated to the load; although this is not a "real" power metering, but merely a conversion factor between activation time and the estimated consumed power, nonetheless it can supply a useful indication for approximate power monitoring, particularly for resistive or fixed-power loads like lights or many other home or office appliances .

The power counter also has an associated KNX "kWh counter" communication object with its own reset command.





6.3 Device settings

This section lists all configurable parameters and describes related communication objects.

Every channel offers the same set of communication objects and parameters, but they may all be independently configured.

Hereafter, a generic channel number is referenced as "x" (where x = 1...8).



The parameter values highlighted in bold represent the default value.

The device settings are divided in two main groups: the general channel configuration settings and the channel-specific settings.

6.3.1 Channels configuration

These settings configure which channels of the device are activated.

Activating a channel causes the creation of a main switching communication object which is the minimal functionality to switch an output relay through a bus telegram.

For outputs 2 and above, instead of being explicitly defined, the channel configuration can be copied from any of the preceding channels. If this option is selected, the corresponding channel can be made to perform the exact same kind of function as the source channel.

This allows to spare time in configuring the device, at the same time assuring that there is no inconsistency between two channels that are meant to be configured in exactly the same way.

It must be noted that to copy the configuration from another channel is just a shortcut for the selection of configuration options; it is in no way implied that the two channels share any of the involved communication objects. If the configuration of the original channel is varied, then so is the "derived" channel; in the same fashion, if the original channel is disabled, so is also the derived one.

| Parameter name | Conditions | Settings | | | |
|-------------------|---|-------------------------------|--|--|--|
| | | disabled | | | |
| Output x | - | enabled | | | |
| | | copy parameters from channel* | | | |
| | Enable output Channel x. | | | | |
| | * This option is only available for channels nr. 2 and above. | | | | |
| Output x – | Output x = | | | | |
| Copy from channel | copy parameters from channel | 1 (x-1) | | | |
| , | | | | | |

| Object name | Conditions | Size | Flags | DPT | CO number(s) |
|-------------------------------|---------------------------------------|--------------------|-----------------|------------------------|------------------------------------|
| Channel X – On/off Command | Channel <i>x</i> = enabled | 1 bit | CRWTU | [1.001] on/off | 0, 19, 38, 57, 76, 95, 114, 133 |
| | This communication object in command. | is the standard "h | nandle" for swi | tching the output thro | ugh a bus |



6.3.2 Channel x configuration

6.3.2.1 Main parameters

In this section most of the configurable parameters for the output are listed.

| Conditions | Settings | | |
|---|--|--|--|
| | not inverted | | |
| - | inverted | | |
| In the "not inverted" mode, the relay contacts (i. output is On (active). | e. the physical output terminals) are shorted when the | | |
| | off | | |
| - | on | | |
| | no change | | |
| | | | |
| | off | | |
| | on | | |
| - | no change | | |
| | previous state | | |
| | put after bus recovery. Indo any output change effected by manually operating the relay | | |
| | off | | |
| - | on | | |
| | no change | | |
| Allows to determine the state of the output when the device resumes operation after a new parametrization has been downloaded. | | | |
| - | enabled / disabled | | |
| Enables or disables the output change notification through a bus telegram. | | | |
| No telegrams are sent after manual operations through the lever switches on the front side. | | | |
| Updating the object from "ON" to "ON" or from "OFF" to "OFF" has no influence on the switching status feedback. | | | |
| | | | |
| Status feedback telegram = enabled | hh:mm:ss.fff | | |
| Ŭ | (00:00:03.000) | | |
| | | | |
| Time after bus voltage recovery before status feedback telegrams begin to be sent. | | | |
| The delay has no effect on the behaviour of the outputs; only the feedback telegrams are delayed. The outputs can therefore be activated during the delay after a bus voltage recovery. | | | |
| During this delay, no feedback telegram will be transmitted even if a switching occurs; the feedback telegram for a switch during the delay period is lost. | | | |
| | In the "not inverted" mode, the relay contacts (i. output is On (active). | | |



| Parameter name | Conditions | Settings | | | |
|---|---|---|--|--|--|
| Status feedback | | j | | | |
| telegram – | | hh:mm:ss | | | |
| Transmission cycle | Status feedback telegram = enabled | (00:00:00) | | | |
| time | | (, | | | |
| | Interval between cyclical transmissions. | | | | |
| | _ | smission (feedback telegrams are only sent on value | | | |
| | change). | | | | |
| | Values less than "00:00:10" (ten seconds) are of seconds; the maximum value is 18:12:15. | considered by the firmware in any case as 10 (ten) | | | |
| On dolay time | | hh:mm:ss.fff | | | |
| On delay time | - | (00:00:00.000) | | | |
| | Delay between the "On" command telegram and | d the actual output activation. | | | |
| | This time delay does not affect the output of the | e staircase and forced control functions. | | | |
| | For the scene function the delay can be set sep | • | | | |
| | Updating the object from "ON" to "ON" or from | | | | |
| Off delay time | _ | hh:mm:ss.fff | | | |
| On delay time | _ | (00:00:00.000) | | | |
| | Delay between the "Off" command telegram and | d the actual output deactivation. | | | |
| | Same comments as for the "On delay time" par | ameter apply. | | | |
| Staircase lighting function | - | enabled / disabled | | | |
| | Enables or disables the staircase lighting feature. | | | | |
| | For further details and parameter descriptions see the corresponding section below. | | | | |
| Locking function | - | enabled / disabled | | | |
| | Enables or disables the capability of locking the input through a remote command. | | | | |
| | For further details and parameter descriptions see the corresponding section below. | | | | |
| Forcing function | - | enabled / disabled | | | |
| | Enables or disables the capability of forcing the input through a remote command. | | | | |
| | For further details and parameter descriptions see the corresponding section below. | | | | |
| | | off | | | |
| Forcing function - | | on | | | |
| Behaviour end | Forcing function = enabled | no change | | | |
| forced control | | previous value | | | |
| | Allows to determine the state of the output when | , | | | |
| | 7 mond to determine the state of the output when | - | | | |
| Forcing function - | | off | | | |
| Behaviour after bus | Forcing function = enabled | on | | | |
| recovery | · | no change | | | |
| | | previous value | | | |
| | Allows to determine the state of the output when the device resumes operation after bus voltage | | | | |
| | recovery. After bus voltage recovery, forcing is implicitly released, and the output value is set according to this setting. | | | | |
| Logic function | - | enabled / disabled | | | |
| | Enables or disables the Logic input conditioning | g feature. | | | |
| For further details and parameter descriptions see the corresponding section below. | | | | | |
| | | | | | |

Release 1.0 - Update: 02/2014



| Parameter name | Conditions | Settings | |
|----------------------------------|---|---------------------------|--|
| Scenes function | - | enabled / disabled | |
| | Enables or disables the Scene function. For further details and parameter descriptions see the corresponding section below. | | |
| Operating hours / energy counter | - | enabled / disabled | |
| | Enables or disables the Hour / Energy counter function. For further details and parameter descriptions see the corresponding section below. | | |

| | | 0. | 1 = | | |
|--------------------|--|--|-------------------|-------------------------|------------------|
| Object name | Conditions | Size | Flags | DPT | CO number(s) |
| Channel x – | Status feedback telegram = | 1 bit | CR-T- | [1.001] switch | 1, 20, 39, 58, |
| On/off status | enabled | | | | 77, 96, 115, 134 |
| | Sent at any change of the o | utput state and a | also periodicall | y, as configured. | • |
| | No telegrams are sent for m | anual operations | s of the relay le | ever switches. | |
| Channel x – | | | | | |
| Staircase lighting | Staircase lighting function = enabled | 1 bit | C-M | [1.001] on/off | 2, 21, 40, 59, |
| start stop command | enabled | | | | 78, 97, 116, 135 |
| Start Stop Sommand | Starts the staircase light tim | ing with an On v | alua. | | |
| | The timed activation automa | • | | oreset time | |
| | If "Manual off" is enabled, th | , , | | | Off value |
| | II Wanda on is enabled, th | le communication | T Object Will St | op the tilling with all | T value. |
| Channel x – | Locking function = | 1 bit C-W | C-W | [1.003] enable | 3, 22, 41, 60, |
| Lock command | enabled | | | | 79, 98, 117, 136 |
| | Inhibits the switching communicks them when a "disab | | | nable" telegram is re | ceived, and |
| Channel x – | Forcing function = | | 0.17 | [2.001] | 4, 23, 42, 61, |
| Forcing command | enabled | 2 bit | C-M | switch control | 80, 99, 118, 137 |
| | Allows to force the status of | an output. | | | • |
| | • | It is composed of 2 bits: the first one is used for the priority value (i.e. defines whether the forcing is in effect, "Priority", or not) and the second one for the imposed value (which is not considered if forcing is not effective). | | | |
| | | 2 hit | Bit | | |

2 bit
Bit number

1 0

0 = off, 1 = on

0 = No priority, 1 = Priority



| Object name | Conditions | Size | Flags | DPT | CO number(s) | |
|--|---|---------------------------------|-----------------|---|--------------------------------------|--|
| Channel x – Scene number | Scene function = enabled | 1 Byte | C-M | [17.001] scene number [18.001] scene control | 13, 32, 51, 70, 89, 108, 127, 146 | |
| | Allows to recall a scene set association to the specified | | s of the output | , and to store current | status in | |
| | | | 1 Byte | | | |
| | | Bit number | | | | |
| | | 7 6 5 | 4 3 2 | 1 0 | | |
| | ' | S | cene numbe | r (1-64) | | |
| | | 0 = recal | not used | | | |
| Channel <i>x</i> – kWh counter | Operating hours / energy counter = enabled | 4-byte signed counter | CR-T- | [13.013] active energy [kWh] | 14, 33, 52, 71, 90, 109, 128, 147 | |
| | Stores the current counter v | alue of the accu | mulated energ | gy. | | |
| Channel <i>x</i> – kWh counter reset command | Operating hours / energy counter = enabled | 1 bit | C-W | [1.015] reset | 15, 34, 53, 72, 91, 110, 129, 148 | |
| | Resets the energy counter | Resets the energy counter to 0. | | | | |
| Channel x – Hours counter | Operating hours / energy counter = enabled | 2-byte unsigned counter | CR-T- | [7.007] time [h] | 16, 35, 54, 73, 92, 111, 130, 149 | |
| | Stores the current counter v | alue of the accu | mulated opera | ating time. | | |
| Channel x – Hours counter reset command | Operating hours / energy counter = enabled | 1 bit | C-W | [1.015] reset | 17, 36, 55, 74, 93, 112, 131, 150 | |
| | Resets the operating hour of | counter to 0. | | • | | |
| Channel <i>x</i> – Hours counter runout | Operating hours / energy counter = enabled | 1 bit | CR-T- | [1.005] alarm | 18, 37, 56, 75, 94, 113, 132, 151 | |
| | 1-bit alarm sent when the ti | me counter reaci | hes the maxim | num value of 65535 ho | purs. | |



6.3.2.2 Staircase lighting function

| Parameter name | Conditions | Settings | | | |
|--------------------|--|---|--|--|--|
| Staircase lighting | Chairean limbhinn from tion — ar ablad | hh:mm:ss | | | |
| time | Staircase lighting function = enabled | (00:01:00) | | | |
| | Duration of staircase lighting time. | | | | |
| | This time is the one shown on the time diagram | in the descriptive section of this manual as " Ts ". | | | |
| Manual off | Staircase lighting function = enabled | enabled / disabled | | | |
| | When enabled, it allows an "Off" command to te | erminate the lighting time. | | | |
| | The "Off" command can be sent at any time with activated. | h the same effect, including when the pre-warning is | | | |
| Retriggerable | Staircase lighting function = enabled | enabled / disabled | | | |
| | When enabled, it allows a new "On" command to | to restart the timing. | | | |
| | The "On" command can be sent at any time with the same effect, including when the pre-warning is activated. | | | | |
| Pre-warning | Staircase lighting function = enabled | enabled / disabled | | | |
| | Activates the pre-warning feature. | | | | |
| | For a detailed description see the corresponding section of this manual. | | | | |
| Pre-warning – | Staircase lighting function = enabled | hh:mm:ss | | | |
| Pre-warning time | Pre-warning = enabled | (00:00:10) | | | |
| | Specifies how much time before the end of the timing a pre-warning light interruption will be carried out. | | | | |
| | The time interval specified includes the interruption time. | | | | |
| | The maximum value is 18:12:15. | | | | |
| | This time is the one shown on the time diagram in the descriptive section of this manual as " Tp-w ". | | | | |
| Pre-warning – | Staircase lighting function = enabled | hh:mm:ss.fff | | | |
| Interruption time | Pre-warning = enabled | Pre-warning = enabled (00:00:00.500) | | | |
| | Specifies the duration of the pre-warning interruption. | | | | |
| | This time is the one shown on the time diagram in the descriptive section of this manual as " Ti ". | | | | |



- The pre-warning time should be shorter than the staircase time $(T_{P-W} < T_S)$ and the interruption time shorter than the pre-warning time $(T_I < T_{P-W})$.
- Time delays have no influence on the staircase function (if enabled).
- A staircase timing in progress will be terminated by a reset of the actuator (bus voltage recovery or ETS reprogramming) or by using any function that affects the output (i.e. normal switching, forced control, logic function, scene recall), even if the function does not cause an actual change in the output value.
 On a forced termination, the value of the output remains unchanged; the same that is true also if the termination occurs during pre-warning time.



6.3.2.3 Locking function

| Parameter name | Conditions | Settings | | |
|------------------------|---|---|--|--|
| Lock device signal | Locking function = enabled | not inverted / inverted | | |
| | Allows to interpret a "lock activate" telegram as | unlock and vice-versa. | | |
| | | unlock | | |
| After bus recovery | Locking function = enabled | lock | | |
| | | previous state | | |
| | Defines how to set the lock status after bus volt | age recovery. | | |
| | | off | | |
| Behaviour at locking | Locking function = enabled | on | | |
| | | no change | | |
| | Defines how to set the output value when the lock is activated. | | | |
| | | off | | |
| Dahardaru | | on | | |
| Behaviour at unlocking | Locking function = enabled | no change | | |
| dillocking | | updated value | | |
| | | value before locking | | |
| | ck is deactivated. | | | |
| | Updated value is the latest one that the output the output value change generated by whatever | would assume if it had not been locked, i.e. it includes rother function in the meantime. | | |

Value before locking is the value that the output had before the lock was activated.



6.3.2.4 Logic function

| Parameter name | Conditions | Settings | | | | |
|--|---|---|--|--|--|--|
| | | OR | | | | |
| Logic operation type | Logic function = enabled | AND | | | | |
| | | XOR | | | | |
| | Defines the logic operation to perform on allow | able inputs. | | | | |
| Read delay after bus | Lawis Constitution and the d | hh:mm:ss.fff | | | | |
| recovery | Logic function = enabled | (00:00:10.000) | | | | |
| | | • | | | | |
| Logic object n | Logic function = enabled | disabled / enabled | | | | |
| | Defines which logic object is used as input. Disabled logic objects are completely ignored a appear. | isabled logic objects are completely ignored and corresponding communication objects do not | | | | |
| Logic object <i>n</i> – Logic object <i>n</i> negated | Logic function = enabled Logic object <i>n</i> = enabled | no / yes | | | | |
| | Applies a logical negation to the value of the input object. | | | | | |

i

The logic function is carried out only if and when at least one of the enabled input objects is updated by a bus telegram.

| Object name | Conditions | Size | Flags | DPT | CO number(s) | |
|---|--|-------|-------|------------------------|--|--|
| Channel <i>x</i> – Logic Object <i>n</i> | Logic function = enabled Logic object <i>n</i> = enabled | 1 bit | CRWTU | [1.*] generic 1-bit | Ch. 1: 512 Ch. 2: 2431 Ch. 3: 4350 Ch. 4: 6269 Ch. 5: 8188 Ch. 6: 100107 Ch. 7: 119126 Ch. 8: 138145 | |
| | For each channel, the CO numbers corresponding to logic objects 1 to 8 are listed. | | | | | |



6.3.2.5 Scenes function

| Parameter name | Conditions | Settings | | | | |
|--------------------------------------|---|---|--|--|--|--|
| Download overwrites learned behavior | Scenes function = enabled | no / yes | | | | |
| | Defines whether the download of a program on the device should erase and overwrite the stored scene output values previously learned and stored in the device. | | | | | |
| | When the device is put into operation for the first time, this parameter should be set to "yes" (default value) so that the output is initialized with valid scene values. Otherwise, the values are set to "0" (off) for all scenes. | | | | | |
| Scene n | Scenes function = enabled | enabled / disabled | | | | |
| | Enables or disables a new scene code to be as | signed to the output. | | | | |
| Scene n – | Scenes function = enabled | 164 | | | | |
| Scene number | Scene <i>n</i> = enabled | (1) | | | | |
| | Scene number to be assigned to the output. The output will respond to scene commands that match the specified number. | | | | | |
| Scene <i>n</i> – Output behavior | Scenes function = enabled Scene n = enabled | off / on | | | | |
| | (Initial) output value for the selected scene. This command if the "Learning mode" option is enable. | s value will be possibly overwritten by a scene "store" oled. | | | | |
| Scene n – | Scenes function = enabled | hh:mm:ss.ff | | | | |
| Activation delay | Scene <i>n</i> = enabled | (00:00:00.00) | | | | |
| | Delay between a scene "recall" command and the maximum value is 01:49:13.50. | the actual output switching. | | | | |
| Scene <i>n</i> – Learning mode | Scenes function = enabled Scene n = enabled | disabled / enabled | | | | |
| L | When disabled, the scene "store" commands as configuration are used. | re ignored and only the output values set in the | | | | |



- Each scene recall telegram restarts the activation delay.
- If a new scene recall telegram is received while a delay is active (scene recall not yet executed), the old and not yet recalled scene will be rejected and the newest scene value will be in effect.
- The scene recall delay has no influence on the saving of scene values when the learning mode is active.
- If the same scene number is set for several scene entries, only the scene with the lowest entry number (1...8) will be considered. The other internal scenes will be ignored in this case.
- The scene recall can be overridden by a forced control or a lock function.



6.3.2.6 Watts / Hours counter

| Parameter name | Conditions | Settings | | | | |
|---------------------|--|----------------------|--|--|--|--|
| Output load [W] | On and the selection of an annual content of | -671088640+670760960 | | | | |
| | Operating hours / energy counter = enabled | (1000) | | | | |
| | Defines the nominal rated power to be considered in computing the accumulated power consumption for the load connected to this output. | | | | | |
| | The total energy consumed [kWh] is calculated as the product of the specified value [W] and the operating hours [h]. | | | | | |
| Consumption / hours | ion / hours hh:mm:ss | | | | | |
| cyclic sending | Operating hours / energy counter = enabled | (00:00:00) | | | | |
| | Defines the time interval for the cyclic retransmission of the counter values (both for accumulated time and energy). | | | | | |
| | A value of zero (00:00:00) disables cyclic transmission. | | | | | |



- Note that manual activation of the lever switches on the front of the device does <u>not</u> affect the counter.
- During ETS programming or bus voltage failure, even if the output is in the "On" position, the counter stops counting.



7 Appendix

7.1 Communication objects table

Following is a summary of all KNX Communication Objects (CO) and corresponding Data Point Types (DPT) defined by the application program according to configuration options.

The listing order is generally by CO number.

| Object name | Conditions | Size | Flags | DPT | CO number(s) | | | |
|--|--|------------------|----------------|---------------------------|------------------------------------|--|--|--|
| Channel X – | Channel x = | 1 hit | 1 bit CRWTU | | 0, 19, 38, 57, | | | |
| On/off Command | enabled | 1 Dit | CIWIO | [1.001] on/off | 76, 95, 114, 133 | | | |
| | This communication object is the standard "handle" for switching the output through a bus command. | | | | | | | |
| Channel <i>x</i> – On/off status | Status feedback telegram = enabled | 1 bit | CR-T- | [1.001] switch | 1, 20, 39, 58, 77, 96, 115, 134 | | | |
| | Sent at any change of the output state and also periodically, as configured. | | | | | | | |
| | No telegrams are sent for manu | al operations of | the relay leve | r switches. | | | | |
| Channel <i>x</i> – Staircase lighting start stop command | Staircase lighting function = enabled | 1 bit | C-W | [1.001] on/off | 2, 21, 40, 59, 78, 97, 116, 135 | | | |
| | Starts the staircase light timing with an On value. The timed activation automatically stops at the end of the preset time. If "Manual off" is enabled, the communication object will stop the timing with an Off value. | | | | | | | |
| Channel x – Lock command | Locking function = enabled | 1 bit | C-M | [1.003] enable | 3, 22, 41, 60, 79, 98, 117, 136 | | | |
| | Inhibits the switching commands for the output when an "enable" telegram is received, and unlocks them when a "disable" telegram is received. | | | | | | | |
| Channel <i>x</i> – Forcing command | Forcing function = enabled | 2 bit | C-M | [2.001] switch control | 4, 23, 42, 61, 80, 99, 118, 137 | | | |
| | Allows to force the status of an | output. | | | | | | |
| | It is composed of 2 bits: the first one is used for the priority value (i.e. defines whether the forcing is in effect, "Priority", or not) and the second one for the imposed value (which is not considered if forcing is not effective). | | | | | | | |
| | | 2 bit | Bit number | | | | | |
| 0 = off, 1 = on | | | | | | | | |
| | 0 = No priority, 1 = Priority | | | | | | | |



| Object name | Conditions | | Size | | FI | Flags | | DPT | CO number(s) |
|--|---|---------------------|------------------------|-------|--------------|---------|--|--|--------------------------------------|
| Channel x – Logic Object n | Logic function = enabled Logic object <i>n</i> = enabled | | 1 bit CRWTU | | | | [1.*] eneric 1-bit | Ch. 1: 512 Ch. 2: 2431 Ch. 3: 4350 Ch. 4: 6269 Ch. 5: 8188 Ch. 6: 100107 Ch. 7: 119126 Ch. 8: 138145 | |
| | For each channel, the listed C | CO r | numbers | corre | spondir | ng to l | ogic c | bjects 1 to 8 | are listed. |
| Channel <i>x</i> – Scene number | Locking function = enabled | | 1 By | C-M | | | [17.001] ene number [18.001] cene control | 13, 32, 51, 70, 89, 108, 127, 146 | |
| | Allows to recall a scene setting for the status of the output, and to store current status in association to the specified scene. 1 Byte Bit number | | | | | | | status in | |
| | | 7 | 6 | 5 4 | 1 3 | 2 | 1 | 0 | |
| | - | scene number (1-64) | | | | | | | |
| | not used 0 = recall, 1 = save | | | | | | | | |
| Channel <i>x</i> – kWh counter | Operating hours / energy counter = enabled | | 4-by signe count | CR | -T- | a | [13.013] ctive energy [kWh] | 14, 33, 52, 71, 90, 109, 128, 147 | |
| | Stores the current counter val | alue (| of the ac | cumu | lated er | nergy. | | | |
| Channel <i>x</i> – kWh counter reset command | Operating hours / energy counter = enabled | | 1 bit | | C-W | | [1 | I.015] reset | 15, 34, 53, 72, 91, 110, 129, 148 |
| | Resets the energy counter to | 0. | | | 1 | | - 1 | | |
| Channel <i>x</i> – Hours counter | Operating hours / energy counter = enabled | | 2-by unsigr coun | CR | -т- | | [7.007] time [h] | 16, 35, 54, 73, 92, 111, 130, 149 | |
| | Stores the current counter value of the accumulated operating time. | | | | | | | | |
| Channel <i>x</i> – Hours counter reset command | Operating hours / energy counter = enabled | | 1 bit | | 1 bit C-W | | [1 | 1.015] reset | 17, 36, 55, 74, 93, 112, 131, 150 |
| | Resets the operating hour col | ounte | er to 0. | | | | • | | |
| Channel <i>x</i> – Hours counter runout | Operating hours / energy counter = enabled | | 1 bi | CR-T- | | [1 | .005] alarm | 18, 37, 56, 75, 94, 113, 132, 151 | |
| | 1-bit alarm sent when the time counter reaches the maximum value of 65535 hours. | | | | | | | | |



7.2 Warning

- Installation, electrical connection, configuration and commissioning of the device can only be carried out by qualified personnel
- · Opening the housing of the device causes the immediate end of the warranty period
- ekinex® KNX defective devices must be returned to the manufacturer at the following address: EKINEX S.p.A. Via Novara 37, I-28010 Vaprio d'Agogna (NO) Italy

7.3 Other information

- · This application manual is aimed at installers, system integrators and planners
- For further information on the product, please contact the ekinex® technical support at the e-mail address: support@ekinex.com or visit the website www.ekinex.com
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